

List of Contents

Volume 2 Number 1

Papers

M. C. LEU 1 Robotics software systems

P. K. WRIGHT 13 A manufacturing hand

J. A. BUZACOTT 25 Modelling manufacturing systems

S. TAKATA, M. OGAWA, P. BERTOK, 33 Real-time monitoring system of tool breakage using Kalman
J. OOTSUKA, K. MATUSHIMA and filtering

T. SATA

S. MAKINOUCHI and K. YAMAGATA 41 Computer numerical control for assuring the machining accuracy
of contour milling

H. ASADA and Y. SAWADA 49 Design of an adaptable tool guide for grinding robots

S. H. KIM and N. P. SUH 55 Application of symbolic logic to the design axioms

T. WATANABE and M. SAKAMOTO 65 On-line scheduling for adaptive control machine tools in FMS

A. ETZIONI and P. JARGOWSKY 75 The two-track society

83 NTIS Reports

i New patents and published patent applications from the United
States and over 30 other countries

xi Software Survey Section

Volume 2 Number 2

Papers

M. E. MERCHANT 89 Computer-integrated manufacturing as the basis for the factory
of the future

J. HATVANY 101 Intelligence and cooperation in heterarchic manufacturing
systems

M. GOLDSTEIN, P. K. WRIGHT and 105 A fast algorithm for high accuracy gauging using computer
D. A. BOURNE vision

G. SPUR, I. FURGAC, A. DEUTSCHLÄNDER, 115 Robot planning system
J. BROWNE and P. O'GORMAN

L. M. SWEET

125 Sensor-based control systems for arc welding robots

D. D. GROSSMAN, R. C. EVANS and
P. D. SUMMERS

135 The value of multiple independent robot arms

S. P. PATARINSKI, M. S. KONSTANTINOV,
V. B. ZAMANOV and D. N. NENCHEV143 Structural properties in kinematics of robots, articulated
mechanisms and prosthetic arms

B. GAÁL and T. VÁRADY

149 Experiences and further development of the FFS (Free-Form
Shapes) CAD/CAM system

155 NTIS Reports

Volume 2 Number 3/4*Editorial*

L. S. HAYNES

161 Opportunities and issues in robot standards

Papers

J. F. BLOODGOOD

165 An overview of standards development for robots and robotic
systemsG. G. HUNT and
J. R. TOMLINSON

191 EIA project 1393: a high level communications standard

M. L. FITZGERALD and
A. J. BARBERA

201 A low-level control interface for robot manipulators

D. GROSSMAN

215 AML as a plant floor language

U. REMBOLD, C. BLUME
and B. J. FROMMHERZ

219 The proposed robot software interfaces SRL and IRDATA

K. LAU, R. HOCKEN
and L. HAYNES227 Robot performance measurements using automatic laser
tracking techniquesN. G. DAGALAKIS and
D. R. MYERS237 Use of coherence analysis for the evaluation and adjustment
of robot gear performanceD. S. ACKERSON and
D. R. HARRY247 Theory, experimental results, and recommended standards
regarding the static positioning and orienting precision
of industrial robotsJ. C. COLSON and
N. D. PERREIRA

261 Quasi-static performance of robots

S. MOHRI, K. TAKEDA,
S. H. K. MATSUZAKI and
Y. HYODO279 Robot language from the standpoint of FA system
development—an outline of FA-BASIC**I Software Survey Section**